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TITLE: AUTOMATIC WELDING DEVICE OF BRANCH PIPE

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ABSTRACT:

PURPOSE: To make construction simple and to enable exact $\underline{\textbf{welding}}$ by

separating a detecting stage for a <u>weld</u> line and a <u>welding</u> stage, and tracing

the groove of the joint detected with a detecting sensor by a $\underline{\text{welding}}$ torch.

CONSTITUTION: A titled device consists of a rotating and driving part 9, a

welding torch 16, a detecting sensor 17 for detecting a groove and a positioning member. Said part 9 is disposed in a device body 8 to be attached

in the open end part of a $\underline{branch\ pipe}$ 2 to be \underline{welded} to a base \underline{pipe} 1 and has

its rotating center in the same position as the axial center of the $\ensuremath{\operatorname{\textbf{pipe}}}\xspace\xspace\xspace 2$.

The torch 16 and the sensor 17 are attached in the part 9 so as to be positioned symmetrically around the axial center of the **pipe** 2 by means of

sliding members 11a, 11b, 15a, 15b which are slidable in the direction at a $\,$

right angle to the axial center of the $\underline{\textbf{pipe}}$ 2 and in the direction parallel

therewith. The joint is detected by the sensor 17 and the torch 16 is controlled to trace the joint according to said detection.

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